



COURSE DESCRIPTION CARD - SYLLABUS

Course name

Diploma seminar [S1AiR1E>SD2]

Course

Field of study

Automatic Control and Robotics

Year/Semester

4/7

Area of study (specialization)

–

Profile of study

general academic

Level of study

first-cycle

Course offered in

English

Form of study

full-time

Requirements

compulsory

Number of hours

Lecture

0

Laboratory classes

0

Other

0

Tutorials

0

Projects/seminars

15

Number of credit points

12,00

Coordinators

dr hab. Marek Kopicki

marek.kopicki@put.poznan.pl

dr hab. inż. Tomasz Pajchrowski prof. PP

tomasz.pajchrowski@put.poznan.pl

prof. dr hab. inż. Piotr Skrzypczyński

piotr.skrzypczynski@put.poznan.pl

prof. dr hab. inż. Dariusz Horla

dariusz.horla@put.poznan.pl

Lecturers

Prerequisites

The student should have basic knowledge of the foundations of robotics, measuring systems, manipulating and mobile robots, robot programming, computer science and artificial intelligence. Should be able to obtain information from the indicated sources. They should also understand the necessity to expand their competences and acquire new skills.

Course objective

The aim of the seminar is to prepare for writing the BSc thesis. During it, the scope of the thesis is reviewed, and a critical review of the literature and existing solutions is made. The aim is also to consolidate the writing and presentation skills.

Course-related learning outcomes

Knowledge:

Is familiar with the current status and latest development trends of the field of automation and robotics [K1_W21 (P6S_WG)].

Knows the methods, techniques, tools and materials used in solving simple engineering tasks in the field of automation and robotics [K1_W23 (P6S_WG)].

Knows and understands the basic concepts and principles of industrial property protection and copyright; is able to use patent information resources [K1_W26 (P6S_WK)].

Skills:

Can communicate using a variety of techniques in professional and other communities [K1_U3 (P6S_UK)].

Can prepare documentation concerning the realisation of an engineering task in Polish and foreign language [K1_U4 (P6S_UW)].

Is able to give a presentation of results on an engineering task in Polish and foreign language [K1_U5 (P6S_UK)].

Has self-education skills to improve and update professional competences [K1_U6 (P6S_UU)].

Is able to use information engineering and communication techniques [K1_U8 (P6S_UW)].

Social competences:

Is ready to critically assess his/her knowledge; understands the need for and knows the possibilities of continuous training - improving professional, personal and social competence, is able to inspire and organize the learning process of others [K1_K1 (P6S_KK)].

Is aware of the responsibility for his/her own work and is ready to follow the rules of teamwork and take responsibility for jointly implemented tasks; is able to lead a small team, set goals and determine priorities leading to the realisation of the task; is ready to play a responsible professional role. [K1_K3 (P6S_KR)].

Is ready to prioritise in order to achieve a task defined by himself or others [K1_K4 (P6S_KO)].

The graduate is aware of the need for a professional approach to technical issues, meticulous familiarization with the documentation and environmental conditions in which the equipment and its components can operate. The graduate is ready to observe the rules of professional ethics and to demand it from others, to respect the diversity of opinions and cultures [K1_K5 (P6S_KR)].

The graduate is ready to fulfil social obligations and co-organise activities for the benefit of the social environment; is aware of the social role of a graduate of a technical university and understands the need to formulate and convey to the public (in particular through the mass media) information and opinions on the achievements of automation and robotics and other aspects of engineering activities; the graduate makes efforts to communicate such information and opinions in a generally understood manner [K1_K7 (P6S_KO)].

Methods for verifying learning outcomes and assessment criteria

Learning outcomes presented above are verified as follows:

Learning outcomes presented above are verified as follows:

Ongoing control of the progress in the preparation of the BSc thesis. Preparation of a presentation showing the progress of work and participation in the discussion on it. The presentations are assessed.

Programme content

Analyzing the subject of the thesis, including a critical review of the literature and comparing it to existing solutions.

Course topics

- Structure and content division of a multimedia presentation on the thesis.
- Key principles and best practices for presenting thesis results and delivering the accompanying lecture.
- Common mistakes and awkwardness during thesis presentation and defense.
- Basic regulations concerning the thesis, including its purpose, copyright issues, and archiving.
- Division of the thesis text into main parts, their significance, text composition, mathematical formulas, tables, figures, evaluation of results, formulation of conclusions, language quality, terminology, bibliography citation, and acceptable use of copyrighted materials.
- Planning tasks and dividing work in group thesis projects (Gantt chart).
- Procedure for preparing, reviewing, and submitting the thesis.
- Procedure for thesis defense and final examination.

Teaching methods

Case study, presentation

Bibliography

Basic

1. A. Dudziak, A. Żejmo, Redagowanie prac dyplomowych – wskazówki metodyczne dla studentów. Difin, 2008
2. J. Maćkiewicz, Jak pisać teksty naukowe?, Uniwersytet Gdański, 2001.
3. P. Oliver, Jak pisać prace uniwersyteckie : poradnik dla studentów, Wyd. Literackie, 1999

Additional

1. J. Pieter, Ogólna metodologia pracy naukowej, Ossolineum, 1967.

Breakdown of average student's workload

	Hours	ECTS
Total workload	30	12,00
Classes requiring direct contact with the teacher	15	1,00
Student's own work (literature studies, preparation for laboratory classes/ tutorials, preparation for tests/exam, project preparation)	15	11,00